

Problem 1.

Consider the 1-forms $\omega_1 = xy dx - z^2 dz$ and $\omega_2 = (2x + z + y) dy$ on \mathbb{R}^3 . Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be the map $f(t, s) = (t + s, e^{t-s}, ts)$.

- (1) Compute the forms $\omega_1 \wedge \omega_2$ and $d(\omega_1 \wedge \omega_2)$.
- (2) Compute the form $f^*(d(\omega_1 \wedge \omega_2))$.
- (3) Consider the singular 1-cube $c : [0, 1] \rightarrow \mathbb{R}^3$ defined as $c(t) = (1, t, t^2)$. Compute $\int_c \omega_1$.

Solution.

1) We have

$$\begin{aligned} \omega_1 \wedge \omega_2 &= (xy dx - z^2 dz) \wedge (2x + z + y) dy = \\ &= (2x^2y + xyz + xy^2) dx \wedge dy - (2xz^2 + z^3 + z^2y) dz \wedge dy = \\ &= (2x^2y + xyz + xy^2) dx \wedge dy + (2xz^2 + z^3 + z^2y) dy \wedge dz. \end{aligned}$$

Hence

$$\begin{aligned} d(\omega_1 \wedge \omega_2) &= \\ \frac{\partial}{\partial z} (2x^2y + xyz + xy^2) dz \wedge dx \wedge dy + \frac{\partial}{\partial x} (2xz^2 + z^3 + z^2y) dx \wedge dy \wedge dz &= \\ xy dz \wedge dx \wedge dy + 2z^2 dx \wedge dy \wedge dz = xy dx \wedge dy \wedge dz + 2z^2 dx \wedge dy \wedge dz &= \\ (xy + 2z^2) dx \wedge dy \wedge dz \end{aligned}$$

2) Since $f^*(d(\omega_1 \wedge \omega_2))$ is a differential 3-form on \mathbb{R}^2 , we have

$$f^*(d(\omega_1 \wedge \omega_2)) = 0.$$

3) We have:

$$\begin{aligned} \int_c \omega_1 &= \int_{[0,1]} c^* \omega_1 = \int_{[0,1]} -(t^2)^2 dt^2 = \\ &= - \int_{[0,1]} 2t^5 dt = - \int_0^1 2t^5 dt = -[t^6/3]_0^1 = -1/3. \end{aligned}$$

Problem 2.

Let $M = \{(x, y, x^2 - y) \in \mathbb{R}^3 \mid x, y \in \mathbb{R}\}$. Then M is a 2-manifold in \mathbb{R}^3 by Problem 5-6 and the map $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $f(x, y) = (x, y, x^2 - y)$, is a coordinate system on M .

Let $p = (0, 0, 0) \in M$ and let $v = (1, 1, 5) \in \mathbb{R}^3$ so that $v_p \in \mathbb{R}_p^3$.

Does v_p belong to M_p ? Provide a proof justifying your answer.

Solution.

We have

$$f'(x, y) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 2x & -1 \end{bmatrix}$$

Thus

$$A := f'(0, 0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix}.$$

By definition M_p consists of all vectors $(Aw)_p$ where $w \in \mathbb{R}^2$. For any $(w_1, w_2) \in \mathbb{R}^2$ we have:

$$A \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} w_1 \\ w_2 \\ -w_2 \end{bmatrix}$$

Suppose $v_p = (1, 1, 5)_p \in M_p$. Then there exists $w = (w_1, w_2) \in \mathbb{R}^2$ such that $(w_1, w_2, -w_2) = (1, 1, 5)$. Obviously, this is impossible, since $1 \neq -5$.

Therefore $v_p \notin M_p$.

Problem 3.

For $n \geq 1$ let $SL(n, \mathbb{R})$ be the set of all $n \times n$ matrices over \mathbb{R} with determinant 1. Let $M(n, \mathbb{R}) = \mathbb{R}^{n^2}$ be the set of all $n \times n$ matrices over \mathbb{R} . Prove that $SL(n, \mathbb{R}) \subseteq M(n, \mathbb{R})$ is a manifold and find the dimension of this manifold.

Solution. We identify $M(n, \mathbb{R})$ with \mathbb{R}^{n^2} and denote the coordinate functions on $M(n, \mathbb{R}) = \mathbb{R}^{n^2}$ by x_{ij} , where $1 \leq i, j \leq n$. Consider the function $f : M(n, \mathbb{R}) \rightarrow \mathbb{R}$ defined as $f(X) := \det(X) - 1$, where $X \in M(n, \mathbb{R})$. Then $SL(n, \mathbb{R}) = f^{-1}(0)$.

The function $f(X) := \det(X) - 1$ is polynomial in the coordinates x_{ij} of X and therefore is smooth. We claim that for any $X \in SL(n, \mathbb{R})$ the derivative $f'|_X : M(n, \mathbb{R}) \rightarrow \mathbb{R}$ is surjective, that is $f'|_X \neq 0$. By Theorem 5.1 this would imply that $SL(n, \mathbb{R}) \subseteq M(n, \mathbb{R}) = \mathbb{R}^{n^2}$ is a manifold of dimension $n^2 - 1$.

Note that if $g_{ij}(t)$, where $1 \leq i, j \leq n$, are differentiable functions of one variable t and

$$G(t) = \begin{vmatrix} g_{11} & \cdots & g_{1n} \\ \vdots & \vdots & \vdots \\ g_{n1} & \cdots & g_{nn} \end{vmatrix}$$

then

$$G'(t) = \begin{vmatrix} g'_{11} & \cdots & g'_{1n} \\ g_{21} & \cdots & g_{2n} \\ \vdots & \vdots & \vdots \\ g_{n1} & \cdots & g_{nn} \end{vmatrix} + \begin{vmatrix} g_{11} & \cdots & g_{1n} \\ g'_{21} & \cdots & g'_{2n} \\ \vdots & \vdots & \vdots \\ g_{n1} & \cdots & g_{nn} \end{vmatrix} + \cdots + \begin{vmatrix} g_{11} & \cdots & g_{1n} \\ g_{21} & \cdots & g_{2n} \\ \vdots & \vdots & \vdots \\ g'_{n1} & \cdots & g'_{nn} \end{vmatrix}$$

Therefore for

$$\frac{\partial f}{\partial x_{ij}} \Big|_X = \frac{\partial}{\partial x_{ij}} \begin{vmatrix} x_{11} & \cdots & x_{1j} & \cdots & x_{1n} \\ x_{21} & \cdots & x_{2j} & \cdots & x_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{i1} & \cdots & x_{ij} & \cdots & x_{in} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} & \cdots & x_{nj} & \cdots & x_{nn} \end{vmatrix} = \begin{vmatrix} x_{11} & \cdots & x_{1j} & \cdots & x_{1n} \\ x_{21} & \cdots & x_{2j} & \cdots & x_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} & \cdots & x_{nj} & \cdots & x_{nn} \end{vmatrix} = (adj X)_{ji}$$

where $adj X$ is the adjoint matrix of X .

If $X \in SL(2, \mathbb{R})$ then $\det(X) = 1$ and hence X is invertible. Moreover, in this case $X^{-1} = \frac{1}{\det(X)} adj X = adj X \neq 0$. Therefore there exist $i, j \in \{1, \dots, n\}$ such that

$$0 \neq (X^{-1})_{ij} = (adj X)_{ji} = \frac{\partial f}{\partial x_{ji}} \Big|_X.$$

Thus $f'|_X \neq 0$, as required.

Problem 4.

Let V be a vector space over \mathbb{R} . A k -tensor $T : V^k \rightarrow \mathbb{R}$ is called *symmetric* if $T(v_1, \dots, v_k) = T(v_{\sigma(1)}, \dots, v_{\sigma(k)})$ for every permutation $\sigma \in S_k$ and for all $v_1, \dots, v_k \in V$. Let $\mathcal{S}_k(V)$ be the set of all symmetric k -tensors on V (so that $\mathcal{S}_k(V)$ is a subspace of the space $\mathcal{T}_k(V)$ of all k -tensors on V).

Construct linear maps $Sym_k : \mathcal{T}_k(V) \rightarrow \mathcal{S}_k(V)$, $k \geq 1$, such that $Sym_k(T) = T$ for any symmetric k -tensor T (with $k \geq 1$) and $Sym_k(T) = 0$ for any alternating k -tensor T (with $k \geq 2$). Prove that the maps you constructed have the required properties.

Solution.

For a k -tensor T and $v_1, \dots, v_k \in V$ put

$$Sym_k(T)(v_1, \dots, v_k) := \frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}).$$

It is clear that Sym_k is a linear map from $\mathcal{T}_k(V)$ to $\mathcal{T}_k(V)$.

1) We claim that if $k \geq 1$ then for any $T \in \mathcal{T}_k(V)$ the tensor $Sym_k(T)$ is symmetric, that is $Sym_k(T) \in \mathcal{S}_k(V)$.

Indeed, let $T \in \mathcal{T}_k(V)$ be arbitrary. Let $\eta \in S_k$ be an arbitrary permutation.

Then for any $v_1, \dots, v_k \in V$ we have

$$\begin{aligned} \text{Sym}_k(T)(v_{\eta(1)}, \dots, v_{\eta(k)}) &= \frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma\eta(1)}, \dots, v_{\sigma\eta(k)}) = \\ &= \frac{1}{k!} \sum_{\sigma \in S_k, \sigma' = \sigma\eta} T(v_{\sigma'(1)}, \dots, v_{\sigma'(k)}) = \\ &= \frac{1}{k!} \sum_{\sigma' \in S_k} T(v_{\sigma'(1)}, \dots, v_{\sigma'(k)}) = \text{Sym}_k(T)(v_1, \dots, v_k). \end{aligned}$$

Thus $\text{Sym}_k(T)$ is symmetric, as required.

2) Suppose that $k \geq 1$ and T is a symmetric k -tensor.

Then for any any $v_1, \dots, v_k \in V$ we have:

$$\begin{aligned} \text{Sym}_k(T)(v_1, \dots, v_k) &:= \frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) = \frac{1}{k!} \sum_{\sigma \in S_k} T(v_1, \dots, v_k) = \\ &= \frac{1}{k!} k! T(v_1, \dots, v_k) = T(v_1, \dots, v_k). \end{aligned}$$

Thus $\text{Sym}_k(T) = T$, as required.

3) Suppose $k \geq 2$ and T is an alternating k -tensor.

Let $\tau := (12) \in S_k$ be the transposition interchanging 1 and 2.

Then for any any $v_1, \dots, v_k \in V$ we have:

$$\begin{aligned} \text{Sym}_k(T)(v_1, v_2, v_3, \dots, v_k) &:= \frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma(1)}, v_{\sigma(2)}, v_{\sigma(3)}, \dots, v_{\sigma(k)}) = \\ &= -\frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma(2)}, v_{\sigma(1)}, v_{\sigma(3)}, \dots, v_{\sigma(k)}) = \\ &= -\frac{1}{k!} \sum_{\sigma \in S_k} T(v_{\sigma\tau(1)}, v_{\sigma\tau(2)}, v_{\sigma\tau(3)}, \dots, v_{\sigma\tau(k)}) = \\ &= -\frac{1}{k!} \sum_{\sigma \in S_k, \sigma' = \sigma\tau} T(v_{\sigma'(1)}, v_{\sigma'(2)}, v_{\sigma'(3)}, \dots, v_{\sigma'(k)}) = \\ &= -\frac{1}{k!} \sum_{\sigma' \in S_k} T(v_{\sigma'(1)}, v_{\sigma'(2)}, v_{\sigma'(3)}, \dots, v_{\sigma'(k)}) = -\text{Sym}_k(T)(v_1, v_2, v_3, \dots, v_k). \end{aligned}$$

Thus $\text{Sym}_k(T)(v_1, v_2, v_3, \dots, v_k) = -\text{Sym}_k(T)(v_1, v_2, v_3, \dots, v_k)$ and therefore $\text{Sym}_k(T)(v_1, v_2, v_3, \dots, v_k) = 0$. Hence $\text{Sym}_k(T) = 0$, as required.