

# Differential Geometry: Problem set 8

November 29, 2006

Due Friday, December 8

1. Complete the proof of Proposition 6.4:

$$(1) \frac{D}{dt}(\xi + \eta) = \frac{D\xi}{dt} + \frac{D\eta}{dt}$$

$$(2) \frac{D}{dt}(\alpha\xi) = \frac{d\alpha}{dt}\xi + \alpha \frac{D\xi}{dt}$$

for any vector fields  $\xi, \eta$  over a curve  $\gamma : (0, 1) \rightarrow M$  and  $\alpha \in C^\infty((0, 1))$ .

2. Compute the Christoffel symbols  $\Gamma_{ij}^k$  for Euclidean space  $\mathbb{R}^n$ , with the standard metric (given by  $g_{ij} = \delta_{ij}$ ).
3. Compute the Christoffel symbols  $\Gamma_{ij}^k$  for the hyperbolic space  $\mathbb{H}^n$  defined in the previous homework.

If  $(M, g)$  is a Riemannian metric, then for every  $m \in M$ ,  $g_m$  defines a nondegenerate pairing

$$T_m M \times T_m M \rightarrow \mathbb{R}$$

and thus a canonical isomorphism  $T_m M \cong T_m^* M$ . This defines an isomorphism

$$\mathfrak{X}(M) \cong \Omega^1 M$$

defined by

$$\xi \mapsto g(\xi, \cdot)$$

we will refer to  $\xi$  and  $g(\xi, \cdot)$  as being *dual* to each other.

- 4 (a) If  $(M^n, g)$  is a Riemannian manifold with local coordinates  $x^1, \dots, x^n$  on an open set  $U$ , prove that there exists vector fields  $\xi_1, \dots, \xi_n \in \mathfrak{X}(U)$  so that for every  $m \in M$ ,  $\xi_1|_m, \dots, \xi_n|_m$  is an orthonormal basis for  $T_m M$ .

(b) Let  $\theta^1, \dots, \theta^n \in \Omega^1 M$  be the dual 1-forms to  $\xi_1, \dots, \xi_n$ . Prove that  $\omega = \theta^1 \wedge \dots \wedge \theta^n$  is a nowhere vanishing top-form.

(c) Prove that if  $\omega$  and  $\omega'$  are defined as above with respect to two different coordinate charts, then  $\omega = \pm\omega'$ .

5 If  $f \in C^\infty(M)$ , then define the gradient of  $f$  to be the dual of  $df$

$$g(\text{grad}(f), \cdot) = df$$

Let  $\phi_t$  be the flow associated to  $\text{grad}(f)$ , and prove that  $f(\phi_t(m)) > f(\phi_s(m))$  if  $t \geq s$  and  $\text{grad}(f)|_m \neq 0$ .

6 Let  $M$  be closed (compact without boundary) and oriented and  $\omega \in \Omega^n M$  be the representative top-form of the orientation which agrees (up to sign) with the form defined in 4(b). If  $\xi \in \mathfrak{X}(M)$ , the *divergence* of  $\xi$  is defined by

$$\text{div}(\xi)\omega = L_\xi\omega \in C^\infty(M)$$

Recall that  $L = dt + \iota d$ , so

$$L_\xi\omega = dt_\xi(\omega)$$

(a) Prove that

$$df \wedge \iota_{\text{grad}(h)}\omega = g(\text{grad}(f), \text{grad}(h))\omega$$

*Hint: For each  $m \in M$ , you can assume  $\text{grad}(h)|_m = c\xi_1|_m$  as in 4(a), for some  $c \in \mathbb{R}$  and some coordinate chart.*

(b) Define  $\Delta : C^\infty(M) \rightarrow C^\infty(M)$  by

$$\Delta(f) = \text{div}(\text{grad}(f))$$

Prove

$$\Delta(fh) = f\Delta h + h\Delta f + 2g(\text{grad}(f), \text{grad}(h)).$$

A function  $f \in C^\infty(M)$  is called *subharmonic* if  $\Delta(f) \geq 0$ ; if  $\Delta(f) = 0$ ,  $f$  is called *harmonic*.

(c) Prove that if  $f$  is a subharmonic function, then  $f$  is harmonic. *Hint: Stokes Theorem.*

(d) Prove that if  $f$  is harmonic, then  $f$  is constant. *Hint: Consider the function  $f^2/2$ , use Stokes again, and part (b).*