

$$1a) \quad \alpha \wedge \beta (V_I) = \sum_{\underline{J} \underline{K}} \delta_{\underline{I}}^{\underline{J} \underline{K}} \alpha(V_{\underline{J}}) \beta(V_{\underline{K}})$$

$$\underline{I} = \{ (1, 2) \}$$

$$\underline{J} \in \{ (1), (2) \}$$

$$\underline{K} \in \{ (2), (1) \}$$

$$\begin{aligned} dx_1 \wedge dx_2 (v_1, v_2) &= \delta_{(1,2)}^{(1,2)} dx_1(v_1) dx_2(v_2) \\ &\quad + \delta_{(1,2)}^{(2,1)} dx_1(v_2) dx_2(v_1) \end{aligned}$$

$$= dx_1(v_1) dx_2(v_2) - dx_1(v_2) dx_2(v_1)$$

$$1b) \quad (dx_1 \otimes dx_2 - dx_2 \otimes dx_1) (v_1, v_2)$$

$$= dx_1(v_1) dx_2(v_2) - dx_2(v_1) dx_1(v_2)$$

$$= dx_1 \wedge dx_2 (v_1, v_2)$$

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2) let's first compute $\alpha \wedge \beta (V_I)$ where

$$\alpha \in \Lambda^2(M) \quad \beta \in \Lambda^1(M) \quad \text{and} \quad I = (1, 2, 3)$$

$$\underline{J} \in \{ (12), (13), (2, 3) \}$$

$$\underline{K} \in \{ (3), (2), (1) \}$$

$$\begin{aligned} \alpha \wedge \beta (V_I) &= \int_{(123)}^{(123)} \alpha(V_1, V_2) \beta(V_3) + \int_{(123)}^{(132)} \alpha(V_1, V_3) \beta(V_2) \\ &\quad + \int_{(123)}^{(231)} \alpha(V_2, V_3) \beta(V_1) \\ &= \alpha(V_1, V_2) \beta(V_3) - \alpha(V_1, V_3) \beta(V_2) \\ &\quad + \alpha(V_2, V_3) \beta(V_1). \end{aligned}$$

$$\text{So } (dx_1 \wedge dx_2) \wedge dx_3 (V_1, V_2, V_3)$$

$$= (dx_1 \wedge dx_2)(V_1, V_2) dx_3(V_3) - (dx_1 \wedge dx_2)(V_1, V_3) dx_3(V_2)$$

$$+ (dx_1 \wedge dx_2)(V_2, V_3) dx_3(V_1)$$

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$$\begin{aligned}
&= \left(dx_1(v_1) dx_2(v_2) - dx_1(v_2) dx_2(v_1) \right) dx_3(v_3) \\
&\quad - \left(dx_1(v_1) dx_2(v_3) - dx_1(v_3) dx_2(v_1) \right) dx_3(v_2) \\
&\quad + \left(dx_1(v_2) dx_2(v_3) - dx_1(v_3) dx_2(v_2) \right) dx_3(v_1)
\end{aligned}$$

Now $dx_1 \wedge (dx_2 \wedge dx_3)(v_1, v_2, v_3)$

$$= - (dx_2 \wedge dx_3) \wedge dx_1(v_1, v_2, v_3)$$

$$= (dx_3 \wedge dx_2) \wedge dx_1(v_1, v_2, v_3)$$

$$\begin{aligned}
&= (dx_3 \wedge dx_2)(v_1, v_2) dx_1(v_3) - (dx_3 \wedge dx_2)(v_1, v_3) dx_1(v_2) \\
&\quad + (dx_3 \wedge dx_2)(v_2, v_3) dx_1(v_1)
\end{aligned}$$

$$= \left(dx_3(v_1) dx_2(v_2) - dx_3(v_2) dx_2(v_1) \right) dx_1(v_3)$$

$$- \left(dx_3(v_1) dx_2(v_3) - dx_3(v_3) dx_2(v_1) \right) dx_1(v_2)$$

$$+ \left(dx_3(v_2) dx_2(v_3) - dx_3(v_3) dx_2(v_2) \right) dx_1(v_1)$$

Comparing terms in both expressions we get the desired equality.

Note $(dx_1 \wedge dx_2) \wedge dx_3 (V_1, V_2, V_3)$
 $= dx_1 \wedge (dx_2 \wedge dx_3) (V_1, V_2, V_3)$
 $= \det (V_1 \ V_2 \ V_3)$

↑ 3×3 matrix with column vectors $V_1, V_2,$ and V_3 .

3) Let (U, ϕ) be a chart in M . To prove that

$$\alpha \wedge \beta = (-1)^{rs} \beta \wedge \alpha \quad \text{it suffices to show}$$

$$\text{that} \quad \alpha^u \wedge \beta^u = (-1)^{rs} \beta^u \wedge \alpha^u.$$

In fact, since $\alpha \wedge (a\beta + b\gamma) = a\alpha \wedge \beta + b\alpha \wedge \gamma$

we can prove this for α^u and β^u of the

$$\text{form} \quad \alpha^u(x) = f(x) dx_1 \wedge \dots \wedge dx_i$$

$$\text{and } \beta^u(x) = g(x) dx_{j_1} \wedge \dots \wedge dx_{j_s}$$

$$\alpha^u(x) \wedge \beta^u(x)$$

$$= (f(x) dx_{i_1} \wedge \dots \wedge dx_{i_r}) \wedge (g(x) dx_{j_1} \wedge \dots \wedge dx_{j_s})$$

$$= f \cdot g(x) dx_{i_1} \wedge \dots \wedge dx_{i_r} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_s}$$

$$= (-1)^r f \cdot g(x) dx_{j_1} \wedge dx_{i_1} \wedge \dots \wedge dx_{i_r} \wedge dx_{j_2} \wedge \dots \wedge dx_{j_s}$$

$$= (-1)^{2r} f \cdot g(x) dx_{j_1} \wedge dx_{j_2} \wedge dx_{i_1} \wedge \dots \wedge dx_{i_r} \wedge dx_{j_3} \wedge \dots \wedge dx_{j_s}$$

⋮

$$= (-1)^{sr} f \cdot g(x) dx_{j_1} \wedge \dots \wedge dx_{j_s} \wedge dx_{i_1} \wedge \dots \wedge dx_{i_r}$$

$$= (-1)^{sr} \beta^u(x) \wedge \alpha^u(x)$$

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5) Show that $d(\alpha^v)(y) = (\phi \circ \psi^{-1})^* (d(\alpha^u)(x))$.

Preliminaries

$$\alpha^u(x) = \sum_i a_i(x) dx_i$$

$$\alpha^v(y) = \sum_j b_j(y) dy_j$$

$$\alpha^v(y) = (\phi \circ \psi^{-1})^* (\alpha^u(x))$$

$$= \sum_i a_i(x(y)) d(x_i(y))$$

$$= \sum_{i,j} a_i(x(y)) \frac{\partial x_i}{\partial y_j} dx_j$$

$$= \sum_j \left(\sum_i a_i(x(y)) \frac{\partial x_i}{\partial y_j} \right) dy_j$$



$$\underline{\underline{b_j(y)}}$$

LHS

let's compute $d(\alpha^v)(y)$.

By Definition

$$d(\alpha^v)(y) = \sum_{k,j} \frac{\partial b_j}{\partial y_k} dy_k \wedge dy_j$$

Since $b_j = \sum_i a_i(x(y)) \frac{\partial x_i}{\partial y_j}$ we have.

$$\frac{\partial b_j}{\partial y_k} = \sum_i \left(\left(\sum_l \frac{\partial a_l}{\partial x_l} \frac{\partial x_l}{\partial y_k} \frac{\partial x_i}{\partial y_j} \right) + a_i(x(y)) \frac{\partial^2 x_i}{\partial y_k \partial y_j} \right)$$

So

$$d(\alpha^v)(y) = \sum_{k,j} \left(\sum_{i,l} \frac{\partial a_l}{\partial x_l} \frac{\partial x_l}{\partial y_k} \frac{\partial x_i}{\partial y_j} \right) dy_k \wedge dy_j$$

$$+ \sum_{k,j} \left(\sum_i \frac{\partial^2 x_i}{\partial y_k \partial y_j} \right) dy_k \wedge dy_j$$

The second sum vanishes. since

$$\frac{\partial^2 x_i}{\partial y_k \partial y_j} dy_k \wedge dy_j = - \frac{\partial^2 x_i}{\partial y_j \partial y_k} dy_j \wedge dy_k.$$

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$$\text{So } d(\alpha^u)(y) = \sum_{k,j} \left(\sum_{i,l} \frac{\partial a_i}{\partial x_l} \frac{\partial x_l}{\partial y_k} \frac{\partial x_i}{\partial y_j} \right) dy_k \wedge dy_j$$

RHS Now we compute $(\phi \circ \psi^{-1})^*(d(\alpha^u)(x))$.

$$\begin{aligned} (\phi \circ \psi^{-1})^*(d(\alpha^u)(x)) &= (\phi \circ \psi^{-1})^* \left(\sum_{i,j} \frac{\partial a_i}{\partial x_j} dx_j \wedge dx_i \right) \\ &= \sum_{i,j} \frac{\partial a_i}{\partial x_j}(\psi(y)) d(x_j(y)) \wedge d(x_i(y)) \\ &= \sum_{i,j} \frac{\partial a_i}{\partial x_j} \left(\sum_k \frac{\partial x_j}{\partial y_k} dy_k \right) \wedge \left(\sum_l \frac{\partial x_i}{\partial y_l} dy_l \right) \\ &= \sum_{i,j} \left(\sum_{k,l} \frac{\partial a_i}{\partial x_j} \frac{\partial x_j}{\partial y_k} \frac{\partial x_i}{\partial y_l} dy_k \wedge dy_l \right) \\ &= \sum_{k,l} \left(\sum_{i,j} \frac{\partial a_i}{\partial x_j} \frac{\partial x_j}{\partial y_k} \frac{\partial x_i}{\partial y_l} \right) dy_k \wedge dy_l \\ &= \text{LHS} \end{aligned}$$

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