

Consider: $\Omega \subset \mathbb{R}^n$ bounded and open

$$I: W^{1,q}(\Omega) \rightarrow \mathbb{R}, \quad 1 < q < \infty$$

$$I[u] = \int_{\Omega} L(Du(x), u(x), x) dx$$

where

$$L: \mathbb{R}^n \times \mathbb{R} \times \Omega \rightarrow \mathbb{R}$$

satisfies Carathéodory conditions:

(i) $L(\cdot, \cdot, x)$ is continuous for almost all $x \in \Omega$

(ii) $L(p, z, \cdot)$ is measurable for all $(p, z) \in \mathbb{R}^n \times \mathbb{R}$

and:

$$(1) \left\{ \begin{array}{l} \exists C_1 > 0 \text{ and } g_1(x) \in L^1(\Omega) \text{ such that:} \\ |L(p, z, x)| \leq C_1(|p|^2 + |z|^2) + g_1(x) \\ \text{for all } (p, z) \in \mathbb{R}^n \times \mathbb{R} \text{ and almost all } x \in \Omega. \end{array} \right.$$

Example $\exists f$

$$L(p_1, p_2, \dots, p_n, z, x) = \frac{1}{2} \sum_{i,j=1}^n a_{ij}(x) p_i p_j + \frac{1}{2} c(x) z^2 + F(x) z$$

then (i), (ii) and (1) hold provided

$a_{ij}, c \in L^\infty(\Omega)$ and $F \in L^2(\Omega)$.

(Use $q=2$ and $|F(x)z| \leq \frac{1}{2} F^2(x) + \frac{1}{2} z^2$)

Lemma 1 If (i) and (ii) are satisfied then, for any measurable functions $g_1, g_2, \dots, g_n, \psi: \Omega \rightarrow \mathbb{R}$, we have

$$L(g_1(\cdot), g_2(\cdot), \dots, g_n(\cdot), \psi(\cdot), \cdot)$$

is measurable. If in addition (1) is also satisfied then I is well defined.

Proof: Since $g_1, g_2, \dots, g_n, \psi$ are measurable there exists the sequences of simple functions

$$\{g_1^k\}_{k \in \mathbb{N}}, \{g_2^k\}_{k \in \mathbb{N}}, \dots, \{g_n^k\}_{k \in \mathbb{N}}, \{\psi^k\}_{k \in \mathbb{N}}$$

such that

$$g_i^k \xrightarrow{\text{a.e.}} g_i \quad \forall i \in \{1, 2, \dots, n\}$$

$$\psi^k \xrightarrow{\text{a.e.}} \psi$$

Then by (i) we have

$$L^k(x) = L(g_1^k(x), g_2^k(x), \dots, g_n^k(x), \psi^k(x), x) \xrightarrow{\text{a.e.}} L(g_1(x), g_2(x), \dots, g_n(x), \psi(x), x)$$

Now fix $k \in \mathbb{N}$. Since $g_1^k, g_2^k, \dots, g_n^k, U^k$ are simple functions there exists $(p_j, z_j) \in \mathbb{R}^n \times \mathbb{R}$ $j \in \{1, 2, \dots, N\}$ such that

$$(g_1^k(x), g_2^k(x), \dots, g_n^k(x), U^k(x)) = \sum_{j=1}^N (p_j, z_j) \chi_j(x)$$

where χ_j is the characteristic function of a measurable set $\Omega_j \subseteq \Omega$ with

$$\bigcup_{j=1}^N \Omega_j = \Omega.$$

Then $L^k \Big|_{\Omega_j} = L(p_j, z_j, \cdot)$ is measurable

for all j hence L^k is measurable.

Finally, L is measurable as the limit a.e. of a sequence of measurable functions L^k .

For $U \in W^{1,2}(\Omega)$ we have

$$DU = \left(\frac{\partial U}{\partial x_1}, \frac{\partial U}{\partial x_2}, \dots, \frac{\partial U}{\partial x_n} \right) \in L^2(\Omega) \times L^2(\Omega) \times \dots \times L^2(\Omega)$$

$$U \in L^2(\Omega)$$

and by the above argument

$$L(DU(\cdot), U(\cdot), \cdot) \text{ is measurable}$$

In addition, from (1) we have a.e. in Ω

$$|L(DU(\cdot), U(\cdot), \cdot)| \leq C_1 \left(\underbrace{|DU(\cdot)|^2}_{L^1(\Omega)} + \underbrace{|U(\cdot)|^2}_{L^1(\Omega)} \right) + \underbrace{g_1(\cdot)}_{\in L^1(\Omega)}$$

So $L(DU(\cdot), U(\cdot), \cdot)$ is integrable on Ω and $|\int_{\Omega} L(DU) < +\infty$. Lemma is proved.

Second assumption is on derivatives of L and visues Gâteaux (even Fréchet) differentiability of I .

(2) For almost all $x \in \Omega$, $L(p_1, p_2, \dots, p_n, z, x)$ has partial derivatives $\frac{\partial L}{\partial p_i}(p, z, x)$, $i=1, \dots, n$ and $\frac{\partial L}{\partial z}(p, z, x)$ at all $(p, z) \in \mathbb{R}^n \times \mathbb{R}$ which are continuous in (p, z) and satisfy for all $(p, z) \in \mathbb{R}^n \times \mathbb{R}$ and $i=1, 2, \dots, n$:

$$\left| \frac{\partial L}{\partial p_i}(p, z, x) \right| \leq C_2 (|p|^{q-1} + |z|^{q-1}) + g_2(x)$$

$$\left| \frac{\partial L}{\partial z}(p, z, x) \right| \leq C_2 (|p|^{q-1} + |z|^{q-1}) + g_2(x)$$

where $C_2 > 0$ and $g_2 \in L^{\frac{q}{q-1}}(\Omega)$, $\frac{1}{q} + \frac{1}{q'} = 1$, are fixed.

Lemma 2 If (i), (ii), (1) and (2) are satisfied then for any $u \in W^{1, q}(\Omega)$ and $v \in W^{1, q}(\Omega)$

$$dI(u)[v] = \lim_{\varepsilon \rightarrow 0} \frac{I(u + \varepsilon v) - I(u)}{\varepsilon} \text{ exists and}$$

$$dI(u)[v] = \int_{\Omega} \sum_{i=1}^n \frac{\partial L}{\partial p_i}(u(x), u(x), x) \frac{\partial v}{\partial x_i}(x) + \frac{\partial L}{\partial z}(u(x), u(x), x) v(x) dx$$

Proof Fix $u, v \in W^{1,2}(\Omega)$

$$dI(u)[v] =$$

$$= \lim_{\varepsilon \rightarrow 0} \int_{\Omega} \frac{L(\nabla u + \varepsilon \nabla v)(x), u + \varepsilon v(x), x) - L(\nabla u(x), u(x), x)}{\varepsilon} dx$$

Denote the integrand above by $L^\varepsilon(x)$. By (2) L is (Fréchet) differentiable in the first $n+1$ variables for almost all x , hence:

$$L^\varepsilon(x) \xrightarrow{\varepsilon \rightarrow 0} \sum_{i=1}^n \frac{\partial L}{\partial p_i}(\nabla u(x), u(x), x) \frac{\partial v}{\partial x_i}(x) + \frac{\partial L}{\partial t}(\nabla u(x), u(x), x) v(x) \quad \text{a.e. in } \Omega$$

Also the mean value theorem and the bounds in (2): we have for almost all $x \in \Omega$ and $0 \leq |\tilde{\varepsilon}(x)| \leq \varepsilon \leq 1$:

$$\begin{aligned} |L^\varepsilon(x)| &\leq \sum_{i=1}^n \left| \frac{\partial L}{\partial p_i}(\nabla u + \tilde{\varepsilon} \nabla v, u + \tilde{\varepsilon} v, x) \right| \left| \frac{\partial v}{\partial x_i}(x) \right| \\ &\quad + \left| \frac{\partial L}{\partial t}(\nabla u + \tilde{\varepsilon} \nabla v, u + \tilde{\varepsilon} v, x) \right| |v(x)| \\ &\leq \sum_{i=1}^n \left[C_2 \left(|\nabla u(x) + \tilde{\varepsilon} \nabla v(x)|^{q_2-1} + |u(x) + \tilde{\varepsilon} v(x)|^{q_2-1} \right) + g_2(x) \right] \left| \frac{\partial v}{\partial x_i}(x) \right| \\ &\quad + \left[C_2 \left(|\nabla u(x) + \tilde{\varepsilon} \nabla v(x)|^{q_2-1} + |u(x) + \tilde{\varepsilon} v(x)|^{q_2-1} \right) + g_2(x) \right] |v(x)| \\ &\leq \sum_{i=1}^n \left[C_2 2^{q_2-2} \left(|\nabla u(x)|^{q_2-1} + |\nabla v(x)|^{q_2-1} + |u(x)|^{q_2-1} + |v(x)|^{q_2-1} \right) + g_2(x) \right] \left| \frac{\partial v}{\partial x_i}(x) \right| \end{aligned}$$

$$+ \underbrace{\left[c_2 2^{\varepsilon-2} (|w_u(x)|^{\varepsilon-1} + |w_v(x)|^{\varepsilon-1} + |u(x)|^{\varepsilon-1} + |v(x)|^{\varepsilon-1} + g_2(x)) \right]}_{\in L^{\varepsilon'}(\Omega)} \underbrace{|v(x)|}_{\in L^{\varepsilon}(\Omega)}$$

$$\leq \tilde{g}_2(x) \in L^1(\Omega)$$

By dominated convergence theorem we can pass to the limit in:

$$dI(u)[v] = \lim_{\varepsilon \rightarrow 0} \int_{\Omega} L^{\varepsilon}(x) dx$$

$$= \int_{\Omega} \sum_{i=1}^n \frac{\partial L}{\partial p_i}(w_u, v, x) \frac{\partial v}{\partial x_i}(x) + \frac{\partial L}{\partial z}(w_u, v, x) v(x) dx.$$

Remark 1 From formula above and continuity of $\frac{\partial L}{\partial p_i}(p, z, x), \frac{\partial L}{\partial z}(p, z, x)$ in (p, z) a.e. $x \in \Omega$ we

deduce that $dI(u)$ is continuous in v hence I is Fréchet differentiable.

Lemma 2 can be proven assuming only that for a.e. $x \in \Omega$, $L(p, z, x)$ has directional derivatives in any direction (p, z) which depends linearly on the direction. In this case I remains Gâteaux differentiable but it may be not Fréchet differentiable.

Theorem 1 Fix $f \in L^2(\partial\Omega)$ such that

$$\mathcal{A} = \{u \in W^{1,2}(\Omega) \mid \text{trace } u = f\} \neq \emptyset.$$

If (i), (ii) (1) and (2) are satisfied and u is a minimizer (maximizer) of \mathcal{I} relative to \mathcal{A} then u is a weak solution of the boundary value problem:

$$(BVP) \begin{cases} -\sum_{i,j=1}^n \frac{\partial}{\partial x_i} \left(\sum_{i,j=1}^n \frac{\partial \mathcal{L}}{\partial p_{ij}}(u, u, x) \right) + \frac{\partial \mathcal{L}}{\partial z}(u, u, x) = 0 \\ u|_{\partial\Omega} = f \end{cases}$$

Remark 2 For the example on page 1 the BVP is:

$$(\widetilde{BVP}) \begin{cases} -\sum_{i,j=1}^n a_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} + c(x)u(x) + F(x) = 0 & x \in \Omega \\ u|_{\partial\Omega} = f \end{cases}$$

Given Lemma 1 & 2 (BVP) should be a direct consequence of Euler-Lagrange equations for constrained minimizers, see Lecture 7. However the constrained $u \in \mathcal{A}$ cannot be written in

the form $G(u) = 0$ for $G: X \rightarrow \mathbb{R}$ (or \mathbb{R}^n).
 As a project you are invited to generalize the result in Lecture 7 such that it can be directly applied to this problem.

Proof of Theorem 1 Fix $w \in \mathcal{A}$, note that

$$\mathcal{A} = w + W_0^{1,2}(\Omega) = \{w+u \mid u \in W_0^{1,2}(\Omega)\}$$

Define $\tilde{I}: W_0^{1,2}(\Omega) \rightarrow \mathbb{R}$ by

$$\tilde{I}(u) = I(w+u)$$

Lemma 1 implies \tilde{I} is well defined while Lemma 2 guarantees \tilde{I} has Gâteaux differential everywhere:

$$\delta \tilde{I}(u)[v] = \delta I(w+u)[v]$$

$$= \int_{\Omega} \sum_{i=1}^n \frac{\partial L}{\partial p_i}(w+u, w+u, x) \frac{\partial v}{\partial x_i}(x) + \frac{\partial L}{\partial z}(w+u, w+u, x) v \, dx$$

for all $v \in W_0^{1,2}(\Omega)$

Moreover if u is a minimizer of I relative

to A then $\tilde{U} = U - w$ is a global minimizer of \tilde{I} on $W_0^{1,2}(\Omega)$. By first theorem in Lecture 7 we must have:

$$\delta \tilde{I}(\tilde{U})[v] = 0 \quad \forall v \in W_0^{1,2}(\Omega)$$

Therefore:

$$(*) \int_{\Omega} \sum_{i=1}^n \frac{\partial L}{\partial p_i}(Du, U, x) \frac{\partial v}{\partial x_i} + \frac{\partial L}{\partial z}(Du, U, x) v \, dx = 0 \quad \forall v \in W_0^{1,2}(\Omega)$$

Hence U is a weak soln of BVP (which require $(*)$ for $v \in C_0^\infty(\Omega)$ only), q.e.d.

To guarantee the existence of a minimum for I coercivity and convexity assumptions are needed:

(3) Coercivity: Assume $I[U] \geq \alpha \|Du\|_{L^2(\Omega)}^2 - \beta$ for some constants $\alpha > 0$, $\beta \in \mathbb{R}$ and any $U \in A$

Now (3) implies coercivity of I on A i.e.

$$\lim_{\|U\|_{W^{1,2}} \rightarrow \infty, U \in A} I[U] = +\infty$$

Indeed $U \in \mathcal{A} \Rightarrow U - w \in W_0^{1,2}(\Omega)$ for some fixed $w \in V$. Since \mathcal{A} is bounded by Poincaré Inequality:

$$\|U - w\|_{L^2} \leq C_p \|DU - Dw\|_{L^2}$$

$$\Rightarrow \|U\|_{L^2} \leq C_p \|DU\|_{L^2} + \max\{1, C_p\} \|w\|_{W^{1,2}(\Omega)}$$

$$\Rightarrow \|U\|_{W^{1,2}(\Omega)} \leq (C_p + 1) (\|DU\|_{L^2} + \|w\|_{W^{1,2}(\Omega)})$$

Since w is fixed, $\|U\|_{W^{1,2}(\Omega)} \rightarrow \infty \quad U \in \mathcal{A}$ implies

$$\|DU\|_{L^2(\Omega)} \rightarrow \infty$$

so by (3) we get

$$\lim I[U] = +\infty.$$

$$\|U\|_{W^{1,2}(\Omega)} \rightarrow \infty$$

$$U \in \mathcal{A}$$

i.e. coercivity of I on \mathcal{A} .

Remark 3 Note that we used \mathcal{A} bounded (in Poincaré Ineq) to show (3) implies coercivity.

Lemma 3 $\forall \mu \exists C_3 > 0, 0 \leq \nu < q,$
 $g_3(x) \in L^d(\Omega)$ with (recall $\Omega \subseteq \mathbb{R}^n$)

$$d = 1 \text{ if } \nu = 0$$

$$\frac{1}{\nu} \left(\frac{1}{\nu} + \frac{1}{n} - \frac{1}{q} \right)^{-1} \leq d \leq \infty \text{ if } q < n$$

$$1 < d \leq \infty \text{ if } q = n$$

$$1 \leq d \leq \infty \text{ if } q > n$$

and $\tilde{g}_3(x) \in L^1(\Omega)$ such that, for almost all $x \in \Omega$:

$$(3') \quad L(\rho, z, x) \geq C_3 |\rho|^q - g_3(x) |z|^n - \tilde{g}_3(x)$$

then (3) is satisfied and Γ is coercive on V .

Proof For any $v \in W^{1,2}(\Omega) \cap V$ we have:

$$L(wv(x), v(x), x) \geq C_3 |wv(x)|^q - g_3(x) |v(x)|^n - \tilde{g}_3(x)$$

a.e. on $x \in \Omega$

hence

$$\Gamma[v] = \int_{\Omega} L(wv, v, x) dx \geq C_3 \|wv\|_{L^2}^q - \|\tilde{g}_3\|_{L^1} - \int_{\Omega} g_3(x) |v(x)|^n dx$$

For the last integral term use generalized Hölder:

$$\int_{\Omega} g_3(x) \cdot |v(x)|^2 dx \leq \|g_3\|_{L^2(\text{meas } \Omega)}^{1/\beta} \|v\|_{L^{2\alpha}}^2$$

where $\frac{1}{2} + \frac{1}{\beta} + \frac{1}{\gamma} = 1$ $1 \leq \alpha, \beta, \gamma \leq \infty$

the range of α in the hypothesis and $1 \leq \beta \leq \infty$ allows us to choose:

$$2 \leq 2\gamma \leq \frac{n\alpha}{n-2} \quad \text{if } n > 2.$$

$$2 \leq 2\gamma < \infty \quad \text{if } n = 2 \text{ and}$$

$$2 \leq 2\gamma \leq \infty \quad \text{if } n \leq 2.$$

Hence by Sobolev Embedding:

$$\|v\|_{L^{2\alpha}} \leq C \|v\|_{W^{1,2}(\Omega)}$$

As before, from Ω bounded and $v \in \mathcal{H} \Leftrightarrow v \in W + W_0^{1,2}(\Omega)$ with $w \in W^{1,2}(\Omega)$ fixed we get via Poincaré Ineq.:

$$\|v\|_{W^{1,2}} \leq (C_p + 1) (\|v\|_{L^2} + \|w\|_{W^{1,2}})$$

In conclusion for $w \in \mathcal{H}$ fixed and $n \leq 2$:

$$\begin{aligned} I[v] &\geq C_3 \|v\|_{L^2}^2 - C \|v\|_{L^2}^{\alpha} - C \|w\|_{W^{1,2}(\Omega)}^{\alpha} - \|g_3\|_{L^1} \\ &\geq \tilde{C}_3 \|v\|_{L^2}^2 - C \|w\|_{W^{1,2}(\Omega)}^{\alpha} - \|g_3\|_{L^1} \end{aligned}$$

and the Lemma is finished.

(4) Convexity: Assume for almost all $x \in \mathcal{R}$ and all $z \in \mathbb{R}$ we have

$$p \mapsto L(p, z, x) \text{ is convex (in } p).$$

Remark 4 (4) does not imply convexity of I but it is sufficient to show its weak lower semicontinuity on \mathcal{A} based on continuity of $p \mapsto L$ in z .

Lemma 4: Assume (i), (ii), (1), (2) and (4) hold then $I: \mathcal{A} \rightarrow \mathbb{R}$ is weakly lower semicontinuous.

Proof Let $u_k \rightarrow u$ in $W^{1,2}(\mathcal{R})$, $\{u_k\} \in \mathcal{A}$.
 We need to show:

$$I[u] \leq \liminf I[u_k] \stackrel{\text{notation}}{=} \ell$$

Fix $w \in \mathcal{R} \Rightarrow \{u_k - w\} \in W_0^{1,2}(\mathcal{R})$ and

$$u_k - w \rightarrow u - w \text{ in } W_0^{1,2}(\mathcal{R})$$

because any linear, continuous functional on $W_0^{1,2}(\mathcal{R})$ can be extended via Hahn-Banach Th to a continuous, linear functional on $W^{1,2}(\mathcal{R})$. In particular $u \in \mathcal{A}$.

Now we choose a subsequence $\{u_{k'}\}$ of $\{u_k\}$ such that $\ell = \liminf I[u_k] = \lim_{k' \rightarrow \infty} I[u_{k'}]$ and

a subsequence $\{v_{k''}\}$ of $\{v_k\}$ such that

$$v_{k''} \xrightarrow{L^2} v \quad \text{and} \quad v_{k''}(x) \rightarrow v(x) \text{ a.e. in } \Omega$$

Note that $\{v_{k''}\}$ exists because $v_{k'} - w \xrightarrow{W_0^{1,2}(\Omega)} v - w$
and $W_0^{1,2}(\Omega) \xrightarrow{\text{compact}} L^2(\Omega)$ since Ω is bounded.

Re-label $\{v_{k''}\}$ by $\{v_k\}$. All in all we have:

$$\begin{aligned} v_k &\xrightarrow{W_0^{1,2}(\Omega)} v \\ v_k &\xrightarrow{L^2(\Omega)} v, \quad v_k \xrightarrow{\text{a.e.}} v \\ \lim_{k \rightarrow \infty} I[v_k] &= I. \end{aligned}$$

First $x \in \Omega$ such that $v_k(x) \rightarrow v(x)$
 $D_p L(p, \cdot, x)$ is continuous $\forall p \in \mathbb{R}^n$, see (2),
and $L(\cdot, z, x)$ is convex $\forall z \in \mathbb{R}$, see (4). Then
by Theorem 1 and Remark 1 in Lecture 7:

$$\begin{aligned} L(Dv_k(x), v_k(x), x) &\geq L(Dv(x), v_k(x), x) \\ &\quad + D_p L(Dv(x), v_k(x), x) [Dv_k(x) - Dv(x)] \end{aligned}$$

Since for almost all $x \in \Omega$ the above properties are valid,
the inequalities above hold a.e. $x \in \Omega$. Integrating
over Ω we get

$$\begin{aligned}
 (*) \quad I[u_k] &\geq \int_{\Omega} L(\nabla u(x), u_k(x), x) dx \\
 &\quad + \int_{\Omega} D_p L(\nabla u(x), u(x), x) [\nabla u_k(x) - \nabla u(x)] dx \\
 &\quad + \int_{\Omega} [D_p L(\nabla u(x), u_k(x), x) - D_p L(\nabla u(x), u(x), x)] [\nabla u_k(x) - \nabla u(x)] dx
 \end{aligned}$$

From $u_k(x) \xrightarrow{\text{a.e.}} u(x)$ and
 $L(p, \cdot, x)$ continuous a.e. $x \in \Omega$, $\forall p \in \mathbb{R}^n$
 $D_p L(p, \cdot, x)$ continuous a.e. $x \in \Omega$, $\forall p \in \mathbb{R}^n$
 we get

$$\begin{aligned}
 L(\nabla u(x), u_k(x), x) &\xrightarrow{\text{a.e.}} L(\nabla u(x), u(x), x) \\
 D_p L(\nabla u(x), u_k(x), x) &\xrightarrow{\text{a.e.}} D_p L(\nabla u(x), u(x), x)
 \end{aligned}$$

and via dominated convergence theorem:

$$\begin{aligned}
 L(\nabla u(\cdot), u_k(\cdot), \cdot) &\xrightarrow{L^1(\Omega)} L(\nabla u(\cdot), u(\cdot), \cdot) \\
 D_p L(\nabla u(\cdot), u_k(\cdot), \cdot) &\xrightarrow{L^{q'}(\Omega)} D_p L(\nabla u(\cdot), u(\cdot), \cdot)
 \end{aligned}$$

Moreover $u_k \xrightarrow{W^{1,q}} u \Rightarrow \nabla u_k \xrightarrow{L^q} \nabla u$ hence

$$\int_{\Omega} D_p L(\nabla u(x), u(x), x) [\nabla u_k(x) - \nabla u(x)] dx \xrightarrow{k \rightarrow \infty} 0$$

fixed element of $(L^{q'})^* = (L^q)^*$

and $u_k \xrightarrow{L^2} u \Rightarrow \exists M > 0$ such that

$$\|u_k - u\|_{L^2} \leq M \quad \forall k \in \mathbb{N}$$

hence by Hölder

$$\begin{aligned} & \int_{\Omega} [D_p L(u(x), u_k(x), x) - D_p L(u(x), u(x), x)] [u_k(x) - u(x)] dx \\ & \leq \|D_p L(u(\cdot), u_k(\cdot), \cdot) - D_p L(u(\cdot), u(\cdot), \cdot)\|_{L^{2'}} \|u_k - u\|_{L^2} \end{aligned}$$

$\longrightarrow 0$ as a product of a seq convergent to zero and a bounded sequence.

In conclusion, by passing to the limit $k \rightarrow \infty$ in (*) we get

$$I = \lim_{k \rightarrow \infty} I[u_k] \geq \int_{\Omega} L(u(x), u(x), x) dx = I[u]$$

and the lemma is finished.

Remark 5 (i) The proof of Lemma 4 also shows that

$$v_k \rightarrow v, \{v_k\} \in \mathcal{A} \Rightarrow v \in \mathcal{A}$$

(ii) If Ω satisfies the cone property, then the same proof and

$$W^{1,2}(\Omega) \overset{\text{compact}}{\hookrightarrow} L^2(\Omega)$$

shows I weakly lower semicontinuous on $W^{1,2}(\Omega)$.

(iii) I weakly lower semicontinuous on \mathcal{A} implies for $w \in \mathcal{A}$ fixed:

$$\tilde{I}[\cdot] = I[\cdot - w]$$

is weakly lower semicontinuous on $W_0^{1,2}(\mathbb{R})$.

Theorem 2 Assume (i), (ii), (1)-(4) are all satisfied then I has at least one global minimum on \mathcal{A} provided \mathcal{A} is nonempty.

Proof Use Lemmas 1 and 4 and the

proof of Theorem 2 in Lecture 7 (general theorem for existence of minimizers) where the argument on the limit being in the admissible set is replaced by Remark 5(i).

Alternately one can fix $w \in A$ and

$$\tilde{I} : W_0^{1,2}(\Omega) \rightarrow \mathbb{R} \quad \tilde{I}[\cdot] = I[\cdot - w]$$

Apply Theorem 2 in Lecture 7 to \tilde{I} (with no constraints, i.e. $G : W_0^{1,2}(\Omega) \rightarrow \mathbb{R}$ $G(\cdot) \equiv 0$).

Then use \tilde{U} is a minimizer of $\tilde{I} \Leftrightarrow \tilde{U} + w$ is a minimizer of I on A . Q.E.D.

Corollary 3 If (i), (ii), (1)-(4) are all satisfied then the boundary value problem

$$\begin{cases} -\sum_{i=1}^m \frac{\partial}{\partial x_i} \left(\frac{\partial L}{\partial p_i}(v, u, x) \right) + \frac{\partial L}{\partial z}(v, u, x) = 0 \\ v|_{\partial\Omega} = f \end{cases}$$

has at least one weak solution provided $f \in W^{1,2}(\Omega)$ where $w = f$.

Proof This is an immediate consequence of Theorems 2 and 1.

For uniqueness:

(4') Assume that for almost all $x \in \Omega$
 $(p, z) \mapsto L(p, z, x)$
is strictly convex in (p, z) .

Corollary 4 If (i), (ii), (1)-(3) and (4') are satisfied then $I: A \rightarrow \mathbb{R}$ is strictly convex, has a unique minimizer, and the boundary value problem

$$(13.1) \quad \begin{aligned} (p) \quad & - \sum_{i=1}^n \frac{\partial}{\partial x_i} \left(\frac{\partial L}{\partial v_i} (u(x), v(x), x) \right) + \frac{\partial L}{\partial z} (u(x), v(x), x) = 0 \\ & u|_{\partial\Omega} = f \end{aligned}$$

has a unique weak sol.

Proof Let $u \neq v \in A$ (note that A is convex).
Fix $t \in (0, 1)$. Then from (4'), for almost all $x \in \Omega$

$$\begin{aligned} & L((1-t)u(x) + tv(x), (1-t)v(x) + tv(x), x) \\ & < (1-t)L(u(x), v(x), x) + tL(v(x), v(x), x) \end{aligned}$$

Integrating over Ω we get

$I((1-t)u + tv) \leq (1-t)I(u) + tI(v)$ hence
 I is strictly convex (actually on $V^{1/2}(U)$).
 Then from Remark 3 in Lecture 7 we get
 that the minimiser is unique. Its existence
 is insured by Theorem 2.

Assume now U is a weak sol of (BVP).
 By definition of weak sol:

$$\delta I(U)[\varphi] = 0 \quad \forall \varphi \in C_0^\infty(\Omega)$$

Since (i), (ii), (1) and (2) imply I Fréchet differentiable
 everywhere, see Remark 1 after Lemma 2, we
 have that I is continuous and:

$$D I(U)[\varphi] = 0 \quad \forall \varphi \in C_0^\infty(\Omega)$$

and by density of $C_0^\infty(\Omega)$ in $V_0^{1/2}(\Omega)$ plus continuity
 of $D I(U)$ we get

$$D I(U)[v] = 0 \quad \forall v \in V_0^{1/2}(\Omega).$$

Moreover, continuity and convexity of I
 implies vice Theorem 1 in Lecture 7 that

$\exists h \in (X_0^{1/2}(U))^*$ such that

$$I(\tilde{v}) \geq I(v) + \langle h, \tilde{v} - v \rangle \quad \forall \tilde{v} \in X_0^{1/2}(U).$$

But for Fréchet differentiable functionals $h = DI(v)$
Hence for any $\tilde{v} \in A$

$$I(\tilde{v}) \geq I(v) + \langle DI(v), \underbrace{\tilde{v} - v}_{\in X_0^{1/2}(U)} \rangle = I(v)$$

So v is a minimiser of I on A and by strict convexity v is unique. QED

Example If

$$L(p_1, p_2, \dots, p_n, z, x) = \frac{1}{2} \sum_{i,j=1}^n a_{ij}(x) p_i p_j \\ + \frac{1}{2} c(x) z^2 + F(x) z$$

then the boundary value problem is:

$$\left(\text{BVP} \right) \begin{cases} - \sum_{i,j=1}^n a_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} + c(x) u(x) + F(x) = 0 & x \in \Omega \\ u|_{\partial\Omega} = f \end{cases}$$

Moreover (i), (ii), (1) and (2) are satisfied provided $a_{ij}(x), c(x) \in L^\infty(\Omega)$, $F \in L^2(\Omega)$.
 (3') which implies (3), see Lemma 3, is satisfied provided $c(x) \geq 0$ a.e. in Ω and:

(Uniform ellipticity condition) $\exists C_1 > 0$ such that for almost all $x \in \Omega$:

$$\sum_{i,j=1}^n a_{ij}(x) \xi_i \xi_j \geq C_1 |\xi|^2 \quad \forall \xi \in \mathbb{R}^n.$$

Note that the uniform ellipticity condition is equivalent to: for almost all $x \in \Omega$

$$\sum_{i,j=1}^n \frac{\partial^2 L}{\partial p_i \partial p_j}(p, z, x) \xi_i \xi_j \geq C |\xi|^2 \quad \forall (p, z) \in \mathbb{R}^n \times \mathbb{R} \quad \forall \xi \in \mathbb{R}^n$$

which implies strict convexity of $p \mapsto L(p, z, x)$ for all z and almost all $x \in \Omega$, hence (4) is satisfied.

Corollary 5 If $a_{ij}, c \in L^\infty(\Omega)$, $F \in L^2(\Omega)$ such that $c(x) \geq 0$ a.e. in Ω and $\exists C_1 > 0$ such that for almost all $x \in \Omega$:

$$\sum_{i,j=1}^n a_{ij}(x) \xi_i \xi_j \geq C_1 |\xi|^2 \quad \forall \xi \in \mathbb{R}^n$$

then $(\widetilde{BV} \cap \mathcal{W})$ has exactly one weak solution.

Proof We already checked that (i), (ii), (1)-(4) are all satisfied, so there is at least one solution according to Corollary 3.

Now (4') is not quite satisfied since

$$L(\rho, (1-t)z_1 + tz_2, x) = (1-t)L(\rho, z_1, x) + tL(\rho, z_2, x)$$

for $z_1 \neq z_2$ and $x \in \Omega$ for which $c(x) = 0$.

But $\Gamma(U)$ remains strictly convex simply because $U \neq V$ in $W^{1,2}(\Omega) \Rightarrow \rho U \neq \rho V$ in $L^2(\Omega)$, so

$$L((1-t)\rho U + t\rho V, (1-t)U + tV, x) < \\ < (1-t)L(\rho U, U, x) + tL(\rho V, V, x)$$

by strict convexity of L in the first n variables and convexity in the rest.

So the argument in Corollary 4 still applies and the weak solution is unique. Q.E.D.