

Solution for Math 415

7/28 ~ 7/29

§ 7.1

3. By definition, linear $\Leftrightarrow T(a\vec{v} + b\vec{w}) = aT(\vec{v}) + bT(\vec{w})$

(a). $T(a\vec{v} + b\vec{w}) = (aV_2 + bW_2, aV_1 + bW_1)$

$aT(\vec{v}) + bT(\vec{w}) = (aV_2 + bW_2, aV_1 + bW_1)$ ✓

(b). $T(a\vec{v} + b\vec{w}) = (aV_1 + bW_1, aV_1 + bW_1)$

$aT(\vec{v}) + bT(\vec{w}) = (aV_1 + bW_1, aV_1 + bW_1)$ ✓

(c). $T(a\vec{v} + b\vec{w}) = (0, aV_1 + bW_1)$

$aT(\vec{v}) + bT(\vec{w}) = (0, aV_1 + bW_1)$ ✓

(d) X $T(0) \neq 0$

(e). $T(a\vec{v} + b\vec{w}) = aV_1 + bW_1 - aV_2 - bW_2$

$aT(\vec{v}) + bT(\vec{w}) = a(V_1 - V_2) + b(W_1 - W_2) = aV_1 + bW_1 - aV_2 - bW_2$ ✓

(f). $T(a\vec{v} + b\vec{w}) = (aV_1 + bW_1)(aV_2 + bW_2)$

$aT(\vec{v}) + bT(\vec{w}) = aV_1V_2 + bW_1W_2$ X

4. (a) $S(T(v)) = S(v) = v$

(b) $S(T(v_1 + v_2)) = S(T(v_1) + T(v_2)) = S(T(v_1)) + S(T(v_2))$ linear,

8. (a). Range of T is $\{(x, 0) : x \in \mathbb{R}\}$.

Kernel of T is $\{(x, y) : x = y\}$.

(b). Range of T is $\{(x, y) : x, y \in \mathbb{R}\}$.

Kernel of T is $\{(x, y, z) : x = y = z = 0\}$.

(c). Range of T is $(0, 0)$.

Kernel of T is \mathbb{R}^2 .

(d). Range of T is $\{(x, x) : x \in \mathbb{R}\}$.

Kernel of T is $\{(0, y) : y \in \mathbb{R}\}$.

11. (a) A is m by n

Then input space V is n by 1 vector

output space W is m by 1 vector.

(b) Av is just linear combination of the columns of A .

Thus range of $T =$ column space of A .

(c) $Av=0 \Rightarrow v \in$ nullspace of A .

Thus kernel of $T =$ nullspace of A .

12. (a) $v = (2, 2) = 2(1, 1)$

$$T(v) = 2T(1, 1) = (4, 4)$$

(b) $v = (3, 1) = (1, 1) + (2, 0)$

$$T(v) = (2, 2) + (2, 0) = (4, 2)$$

(c) $v = (-1, 1) = (1, 1) - (2, 0)$

$$T(v) = (2, 2) - (2, 0) = (0, 2)$$

(d) $v = (a, b) = c(1, 1) + d(2, 0)$ find c and $d = c = b$.

$$T(v) = c(2, 2) + d(2, 0) = c(2, 2) = b(2, 2).$$

§ 7.2.

1. $SV_1 = 0$, $SV_2 = 0$, $SV_3 = 2 = 2W_1$, $SV_4 = (3x^2)' = 6x = 6W_2$.

Thus
$$B = \begin{pmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

2. $v'' = 0 \Rightarrow v' = c \Rightarrow v = cx + d$.

kernel of S is {f linear functions}.

The nullspace of B is $\{1, x\} =$ kernel of S .

3. Add a ^{zero} row to the first derivative matrix, we get

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = B.$$

output basis = input basis

$$4. (a) AB = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

This is the transformation matrix for the third derivative with basis $\{1, x, x^2, x^3\}$.

(b) Apply the fourth derivative to the basis, we get zero for all the elements. Thus the transformation matrix B^2 is zero.

$$5. T[v_1, v_2, v_3] = [w_2, w_1 + w_3, w_1 + w_3] \Rightarrow$$

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$A \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$$

$$T(v_1 + 2v_2 + v_3) = T(w_1) + T(v_2) + T(v_3) = 2w_1 + w_2 + 2w_3.$$

6. $v = \cancel{a} (v_2 - v_3)$ (suppose $v = av_1 + bv_2 + cv_3$, solve $T(v) = 0$ by independence of w_1, w_2, w_3 , the coefficients all be zero)
 $(0, a, -a)$ are in the nullspace of A

$$T(v) = w_2 \Rightarrow a w_2 + (b+c)(w_1 + w_3) = w_2$$

$$\Rightarrow (a-1)w_2 + (b+c)(w_1 + w_3) = 0$$

$$\Rightarrow a = 1, \quad b = -c.$$

$$v = v_1 + c(v_2 - v_3).$$

7. Since the column space are span $\{(0, 1, 0), (1, 0, 1)\}$.

The vector not in the column space could be (not unique)
 $(0, 0, 1)$.

Correspondingly, we can choose $w = w_3$, it's not in the range of T .